

Exercise 1. Clearly, the function f is of class C^2 on \mathbb{R}^2 , hence f admits a second order Taylor-Young expansion at $(1, 2)$. For all $(x, y) \in \mathbb{R}^2$,

$$\begin{aligned} \partial_1 f(x, y) &= (x+1)e^{x+2y}, & \partial_1 f(1, 2) &= 2e^5, \\ \partial_2 f(x, y) &= 2xe^{x+2y}, & \partial_2 f(1, 2) &= 2e^5, \\ \partial_{1,1}^2 f(x, y) &= (x+2)e^{x+2y}, & \partial_{1,1}^2 f(1, 2) &= 3e^5, \\ \partial_{1,2}^2 f(x, y) &= 2(x+1)e^{x+2y}, & \partial_{1,2}^2 f(1, 2) &= 4e^5, \\ \partial_{2,2}^2 f(x, y) &= 4xe^{x+2y}, & \partial_{2,2}^2 f(1, 2) &= 4e^5. \end{aligned}$$

Hence the second order Taylor-Young formula of f at $(1, 2)$ is:

$$f(x, y) \underset{(x,y) \rightarrow (1,2)}{=} e^5 + 2e^5(x-1) + 2e^5(y-2) + \frac{3}{2}e^5(x-1)^2 + 4e^5(x-1)(y-2) + 2e^5(y-2)^2 + o(\|(x-1, y-2)\|^2).$$

Exercise 2.

1. The function g is of class C^1 on \mathbb{R}^2 as the composition of the linear mapping $\varphi : (u, v) \mapsto (2u+v, u+v)$ and of the function f which is of class C^1 on \mathbb{R}^2 . Moreover, for all $(u, v) \in \mathbb{R}^2$, by the chain rule:

$$\begin{aligned} \partial_1 g(u, v) &= 2\partial_1 f(2u+v, u+v) + \partial_2 f(2u+v, u+v), \\ \partial_2 g(u, v) &= \partial_1 f(2u+v, u+v) + \partial_2 f(2u+v, u+v). \end{aligned}$$

2. The linear mapping $\varphi : (u, v) \mapsto (2u+v, u+v)$ is a bijection from \mathbb{R}^2 to \mathbb{R}^2 and its inverse is: $\varphi^{-1} : (x, y) \mapsto (x-y, -x+2y)$. Let $(x, y) \in \mathbb{R}^2$. Then:

$$\partial_1 f(x, y) + \partial_2 f(x, y) + (2y-x)f(x, y) = \partial_2 g(x-y, -x+2y) + (2y-x)g(x-y, -x+2y).$$

Hence f is a solution of Equation (E) on \mathbb{R}^2 if and only if:

$$\forall (x, y) \in \mathbb{R}^2, \quad \partial_2 g(x-y, -x+2y) + (2y-x)g(x-y, -x+2y) = 0.$$

Since φ is a bijection from \mathbb{R}^2 to \mathbb{R}^2 , this is also equivalent to:

$$\forall (u, v) \in \mathbb{R}^2, \quad \partial_2 g(u, v) + vg(u, v) = 0.$$

3. We can consider the auxiliary differential equation:

$$y'(u) + vy(u) = 0$$

(where the variable is u and v is a constant). The general solution of this differential equation is

$$y(u) = Ae^{-vu}.$$

Hence the general solution of class C^1 of Equation (E') on \mathbb{R}^2 is:

$$g(u, v) = A(v)e^{-vu}$$

where A is a function of class C^1 on \mathbb{R} .

4. Hence, f is a solution of class C^1 on \mathbb{R}^2 of Equation (E) if and only if f has the form

$$f(x, y) = A(-x+2y)e^{(x-2y)(x-y)}$$

where A is of class C^1 on \mathbb{R} .

Exercise 3.

1. a) Since U is an open set in $(E, \|\cdot\|)$ and since $a_0 \in U$, there exists $r > 0$ such that the open ball centered at a_0 of radius r (denoted by $\hat{B}_r(a_0)$) is included in U . If $h = 0_E$, take $\varepsilon = 42 > 0$ and if $h \neq 0_E$, take $\varepsilon = r/\|h\| > 0$. With this ε we do have $\forall t \in (-\varepsilon, \varepsilon)$, $a_0 + th \in \hat{B}_r(a_0)$ and hence $a_0 + th \in U$.

b) Let $t \in (0, \varepsilon)$. Then, since $f_1 \leq f_2$ throughout U and since $f_1(a_0) = f_2(a_0)$ we have:

$$f_1(a_0 + th) - f_1(a_0) \leq f_2(a_0 + th) - f_2(a_0)$$

and since $t > 0$,

$$\frac{f_1(a_0 + th) - f_1(a_0)}{t} \leq \frac{f_2(a_0 + th) - f_2(a_0)}{t}.$$

Now taking the limit as $t \rightarrow 0^+$ (which is valid since $(0, \varepsilon)$ is a right-sided punctured neighborhood of 0) yields, by definition of the directional derivative,

$$\nabla_h f_1(a_0) \leq \nabla_h f_2(a_0).$$

c) If $t \in (-\varepsilon, 0)$, we'll obtain:

$$\frac{f_1(a_0 + th) - f_1(a_0)}{t} \geq \frac{f_2(a_0 + th) - f_2(a_0)}{t},$$

and taking the limit as $t \rightarrow 0^-$ yields:

$$\nabla_h f_1(a_0) \geq \nabla_h f_2(a_0).$$

2. We proved that for all $h \in E$, $\nabla_h f_1(a_0) = \nabla_h f_2(a_0)$ or, equivalently, for all $h \in E$, $d_{a_0} f_1(h) = d_{a_0} f_2(h)$. Hence $d_{a_0} f_1 = d_{a_0} f_2$.

3. First observe that $g(a_0) = f_1(a_0) = f_2(a_0)$. Hence, from the assumptions and the fact that $d_{a_0} f_1 = d_{a_0} f_2$, we obtain,

$$\forall x \in U, \quad f_1(x) - f_1(a_0) - d_{a_0} f_1(x - a_0) \leq g_1(x) - g_1(a_0) - d_{a_0} f_1(x - a_0) \leq f_2(x) - f_2(a_0) - d_{a_0} f_2(x - a_0)$$

and hence for all $x \in U \setminus \{a_0\}$,

$$\frac{f_1(x) - f_1(a_0) - d_{a_0} f_1(x - a_0)}{\|x - a_0\|} \leq \frac{g_1(x) - g_1(a_0) - d_{a_0} f_1(x - a_0)}{\|x - a_0\|} \leq \frac{f_2(x) - f_2(a_0) - d_{a_0} f_2(x - a_0)}{\|x - a_0\|}.$$

Now, since:

$$\lim_{\|x - a_0\| \rightarrow 0} \frac{f_1(x) - f_1(a_0) - d_{a_0} f_1(x - a_0)}{\|x - a_0\|} = 0$$

and

$$\lim_{\|x - a_0\| \rightarrow 0} \frac{f_2(x) - f_2(a_0) - d_{a_0} f_2(x - a_0)}{\|x - a_0\|} = 0$$

we obtain, by the Squeeze Theorem:

$$\lim_{\|x - a_0\| \rightarrow 0} \frac{g(x) - g(a_0) - d_{a_0} f_1(x - a_0)}{\|x - a_0\|} = 0.$$

The mapping $d_{a_0} f_1$ being linear and continuous on E , we can conclude, from the definition of differentiability, that g is differentiable at a_0 and that $d_{a_0} g = d_{a_0} f_1$.

Exercise 4. First observe that $M_2(\mathbb{R})$ is a finite-dimensional vector space over \mathbb{R} (as it is of dimension 4), hence all the norms on $M_2(\mathbb{R})$ are equivalent. We'll use the norm n defined by:

$$n \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) = |a| + |b| + |c| + |d|.$$

This mapping n is indeed a norm on $M_2(\mathbb{R})$ as the mapping

$$\begin{aligned} \varphi : M_2(\mathbb{R}) &\longrightarrow \mathbb{R}^4 \\ \begin{pmatrix} a & b \\ c & d \end{pmatrix} &\longmapsto (a, b, c, d) \end{aligned}$$

is a *linear bijection* and clearly, for all A , $n(A) = \|\varphi(A)\|_1$.

Let $h \in M_2(\mathbb{R})$, say $h = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$. Then:

$$\begin{aligned} \det(I+h) &= \det \begin{pmatrix} 1+\alpha & \beta \\ \gamma & 1+\delta \end{pmatrix} \\ &= (1+\alpha)(1+\delta) - \beta\gamma \\ &= 1 + \alpha + \delta + (\alpha\delta - \beta\gamma) \\ &= 1 + \operatorname{tr}(h) + (\alpha\delta - \beta\gamma). \end{aligned}$$

Hence,

$$|\det(I+h) - \det(I) - \operatorname{tr}(h)| = |\alpha\delta - \beta\gamma| \leq |\alpha\delta| + |\beta\gamma| \leq 2n(h)^2.$$

Hence:

$$\frac{|\det(I+h) - \det(I) - \operatorname{tr}(h)|}{n(h)} \leq 2n(h) \xrightarrow{n(h) \rightarrow 0} 0.$$

Now, tr is clearly linear (and continuous since we're in a finite-dimensional vector space). Hence \det is differentiable at I and $d_I \det = \operatorname{tr}$.